

Today's outline - March 24, 2022





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- Improving Grover's algorithm



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 - (a) Modifying the iteration distance



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 - (a) Modifying the iteration distance
 - (b) Modifying the last iteration



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- Solving for t



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 - (a) Repeated random iterations



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 - (b) Quantum counting



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Reading assignment: 10.1 – 10.3



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Reading assignment: 10.1 – 10.3

Homework Assignment #06:

See Blackboard

Due Thursday, March 31, 2022

Quantum circuit simulator <https://algassert.com/quirk>



Improving Grover's algorithm

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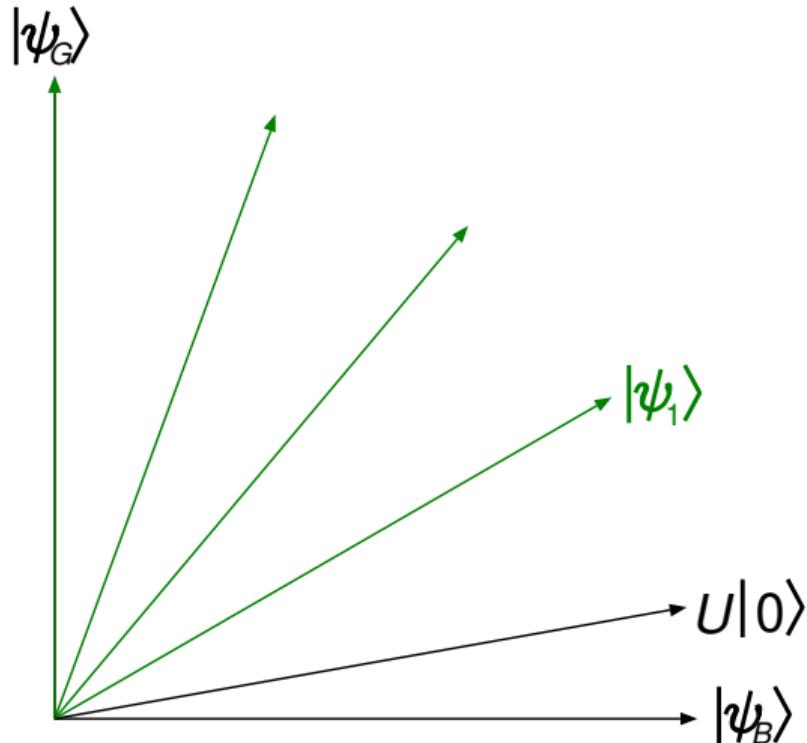
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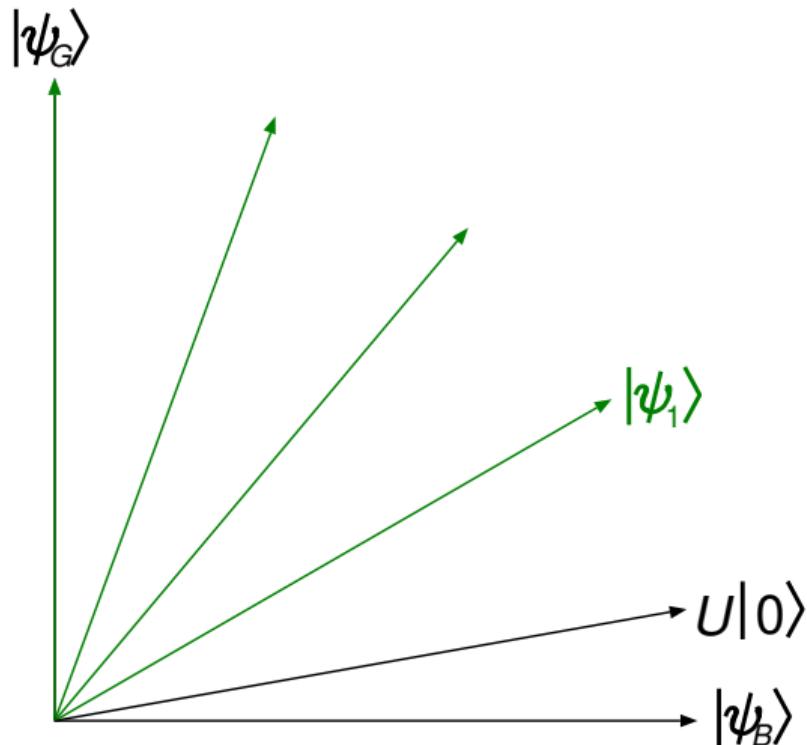
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Thus it is possible to improve on it and guarantee a solution with quadratic speedup



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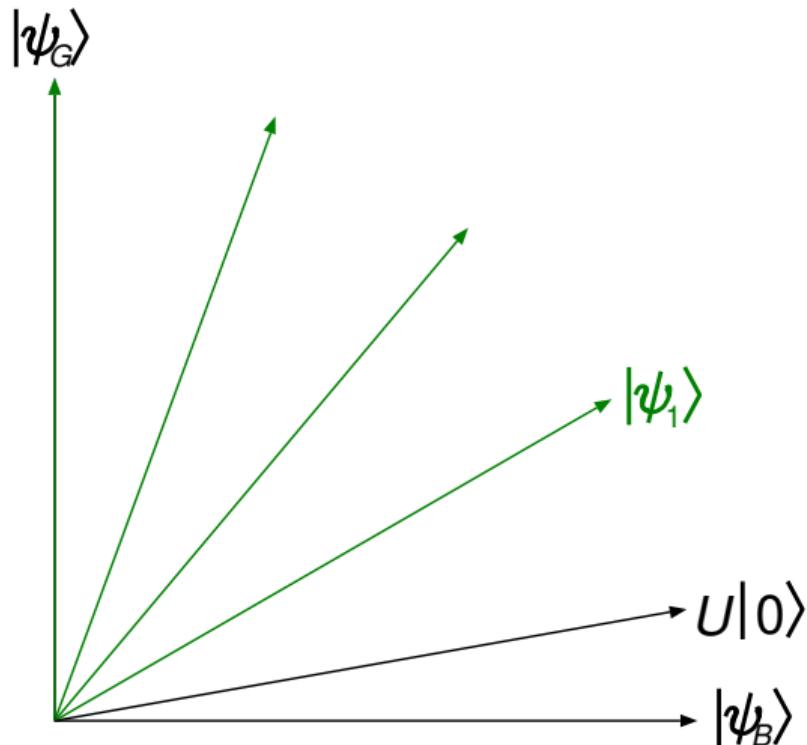
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There are two different methods to accomplish this





Modifying each step

Recall that the probability t is related to an angle θ



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This algorithm now succeeds with certainty in $i = \frac{\pi}{4\theta'} - \frac{1}{2}$ steps



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$$|\psi_s\rangle = \sin[(2s+1)\theta]|\psi_G\rangle + \cos[(2s+1)\theta]|\psi_B\rangle, \quad \sin \theta = \sqrt{t} = g_0$$



Modifying the last step

$$\begin{aligned} US_0^\phi U^{-1} |v\rangle &= U \left(\sum_{i=1}^{N-1} \overline{\langle v|U|i\rangle} |i\rangle + \overline{\langle v|U|0\rangle} e^{i\phi} |0\rangle \right) = \sum_{i=1}^{N-1} \overline{\langle v|U|i\rangle} U|i\rangle + e^{i\phi} \overline{\langle v|U|0\rangle} U|0\rangle \\ &= \sum_{i=0}^{N-1} \overline{\langle v|U|i\rangle} U|i\rangle - \overline{\langle v|U|0\rangle} U|0\rangle + e^{i\phi} \overline{\langle v|U|0\rangle} U|0\rangle = |v\rangle - (1 - e^{i\phi}) \overline{\langle v|U|0\rangle} U|0\rangle \end{aligned}$$

Now applying $Q(\phi, \tau) = US_0^\phi U^{-1} S_G^\tau$ on the superposition $|v\rangle = g|v_G\rangle + b|v_B\rangle$

$$Q(\phi, \tau)|v\rangle = g[-e^{i\tau}|v_G\rangle + e^{i\tau}(1 - e^{i\phi})\overline{\langle v_G|U|0\rangle} U|0\rangle] + b[-|v_B\rangle + (1 - e^{i\phi})\overline{\langle v_B|U|0\rangle} U|0\rangle]$$

After $s = \lfloor \frac{\pi}{4\theta} - \frac{1}{2} \rfloor$ iterations of amplification, we have the state

$$|\psi_s\rangle = \sin[(2s+1)\theta]|\psi_G\rangle + \cos[(2s+1)\theta]|\psi_B\rangle, \quad \sin \theta = \sqrt{t} = g_0$$

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$$\begin{aligned}
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Modifying the last step

$$\begin{aligned}
 US_0^\phi U^{-1} |\nu\rangle &= U \left(\sum_{i=1}^{N-1} \overline{\langle \nu | U | i \rangle} |i\rangle + \overline{\langle \nu | U | 0 \rangle} e^{i\phi} |0\rangle \right) = \sum_{i=1}^{N-1} \overline{\langle \nu | U | i \rangle} U |i\rangle + e^{i\phi} \overline{\langle \nu | U | 0 \rangle} U |0\rangle \\
 &= \sum_{i=0}^{N-1} \overline{\langle \nu | U | i \rangle} U |i\rangle - \overline{\langle \nu | U | 0 \rangle} U |0\rangle + e^{i\phi} \overline{\langle \nu | U | 0 \rangle} U |0\rangle = |\nu\rangle - (1 - e^{i\phi}) \overline{\langle \nu | U | 0 \rangle} U |0\rangle
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$$Q(\phi, \tau)|\psi\rangle = g(\phi, \tau)|\psi_G\rangle + b(\phi, \tau)|\psi_B\rangle$$



Modifying the last step

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The goal is to find values for ϕ and τ such that when the final iteration $Q(\phi, \tau) = US_0^\phi U^{-1}S_G^\tau$ is applied the solution is obtained with certainty



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$$e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}\sin[(2s+1)\theta] = [1 - (1 - e^{i\phi})(1 - g_0^2)]\cos[(2s+1)\theta]$$



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$$\cot[(2s+1)\theta] = \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}}$$



Modifying the last step

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First find ϕ and then choose τ to make the right side of the equation real



Modifying the last step

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Compute the modulus squared of the right side of the equation to make it real



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$$\frac{e^{-i\tau}(1 - e^{-i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{-i\phi}) + e^{-i\phi}} \cdot \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}}$$

Modifying the last step

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Compute the modulus squared of the right side of the equation to make it real

$$\begin{aligned} & \frac{e^{-i\tau}(1 - e^{-i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{-i\phi}) + e^{-i\phi}} \cdot \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}} \\ &= \frac{(2 - e^{i\phi} - e^{-i\phi})g_0^2(1 - g_0^2)}{g_0^4(2 - e^{i\phi} - e^{-i\phi}) + g_0^2(e^{i\phi} + e^{-i\phi} - 2) + 1} = \frac{g_0^2 b_0^2 (2 - 2 \cos \phi)}{g_0^4 (2 - 2 \cos \phi) - g_0^2 (2 - 2 \cos \phi) + 1} \end{aligned}$$

This can be maximized when $\cos \phi = -1$

which then gives

Modifying the last step

$$\cot[(2s+1)\theta] = \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}}$$

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$$\frac{4g_0^2 b_0^2}{4g_0^4 - 4g_0^2 + 1}$$

Modifying the last step

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$$\frac{4g_0^2 b_0^2}{4g_0^4 - 4g_0^2 + 1} = \frac{4g_0^2 b_0^2}{(2g_0^2 - 1)^2}$$

Modifying the last step

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$$\frac{4g_0^2 b_0^2}{4g_0^4 - 4g_0^2 + 1} = \frac{4g_0^2 b_0^2}{(2g_0^2 - 1)^2}$$

Taking the square root gives the maximum magnitude

Modifying the last step

$$\cot[(2s+1)\theta] = \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}}$$

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Compute the modulus squared of the right side of the equation to make it real

$$\begin{aligned} & \frac{e^{-i\tau}(1 - e^{-i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{-i\phi}) + e^{-i\phi}} \cdot \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}} \\ &= \frac{(2 - e^{i\phi} - e^{-i\phi})g_0^2(1 - g_0^2)}{g_0^4(2 - e^{i\phi} - e^{-i\phi}) + g_0^2(e^{i\phi} + e^{-i\phi} - 2) + 1} = \frac{g_0^2 b_0^2(2 - 2 \cos \phi)}{g_0^4(2 - 2 \cos \phi) - g_0^2(2 - 2 \cos \phi) + 1} \end{aligned}$$

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$$\frac{4g_0^2 b_0^2}{4g_0^4 - 4g_0^2 + 1} = \frac{4g_0^2 b_0^2}{(2g_0^2 - 1)^2}$$

$$\frac{2g_0 b_0}{2g_0^2 - 1}$$

Modifying the last step

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First find ϕ and then choose τ to make the right side of the equation real

Compute the modulus squared of the right side of the equation to make it real

$$\begin{aligned} & \frac{e^{-i\tau}(1 - e^{-i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{-i\phi}) + e^{-i\phi}} \cdot \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}} \\ &= \frac{(2 - e^{i\phi} - e^{-i\phi})g_0^2(1 - g_0^2)}{g_0^4(2 - e^{i\phi} - e^{-i\phi}) + g_0^2(e^{i\phi} + e^{-i\phi} - 2) + 1} = \frac{g_0^2 b_0^2(2 - 2 \cos \phi)}{g_0^4(2 - 2 \cos \phi) - g_0^2(2 - 2 \cos \phi) + 1} \end{aligned}$$

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$$\frac{4g_0^2 b_0^2}{4g_0^4 - 4g_0^2 + 1} = \frac{4g_0^2 b_0^2}{(2g_0^2 - 1)^2}$$

$$\frac{2g_0 b_0}{2g_0^2 - 1} = \frac{2g_0 b_0}{g_0^2 - b_0^2}$$

Modifying the last step

$$\cot[(2s+1)\theta] = \frac{e^{i\tau}(1 - e^{i\phi})g_0\sqrt{1 - g_0^2}}{g_0^2(1 - e^{i\phi}) + e^{i\phi}}$$

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This can be maximized when $\cos \phi = -1$

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The right side can be any value from 0 to $\tan(2\theta)$ so the last step can be adjusted as needed

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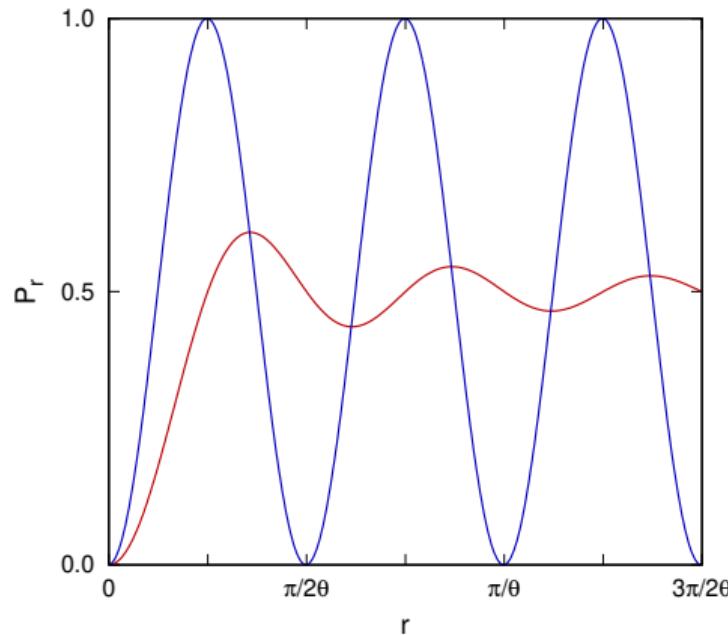
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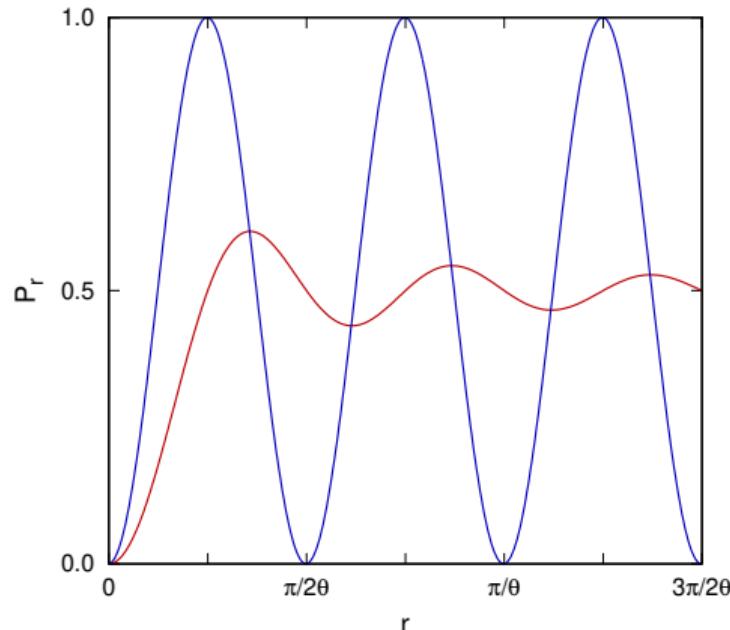


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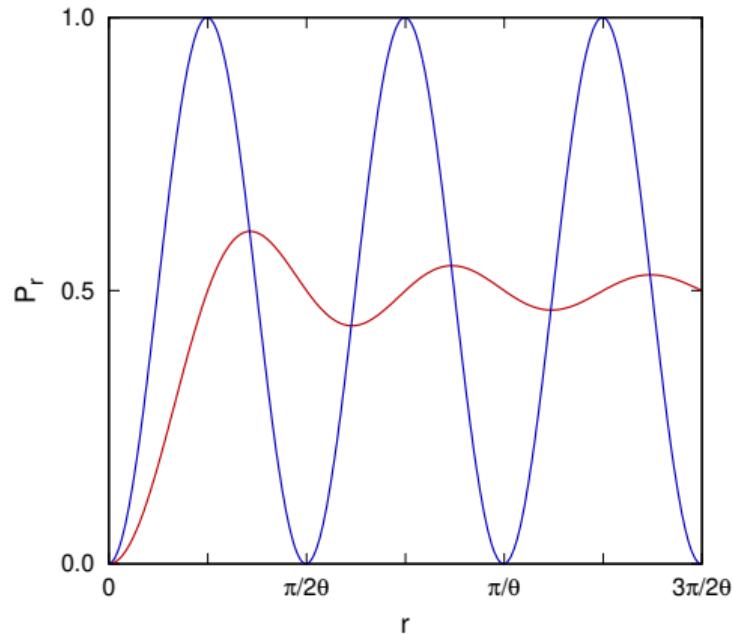
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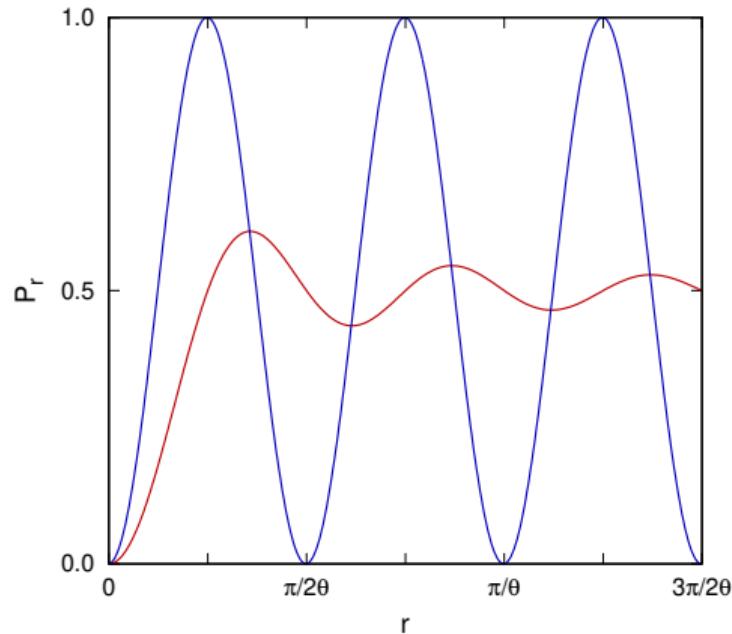
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This means that the expected number of calls to the oracle is $O(\sqrt{N})$





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M can be determined by repeating this algorithm with increasing values of M until j is measured to be a non-zero value